

SECTION 26 29 13.03

MANUAL AND MAGNETIC MOTOR CONTROLLERS

PART 1 - GENERAL

1.1 RELATED DOCUMENTS

- A. Drawings and general provisions of the Contract, including General and Supplementary Conditions and Division 01 Specification Sections, apply to this Section.

1.2 SUMMARY

- A. Section Includes:
 - 1. Manual motor controllers.
 - 2. Enclosed full-voltage magnetic motor controllers.
 - 3. Combination full-voltage magnetic motor controllers.

1.3 DEFINITIONS

- A. CPT: Control power transformer.
- B. MCCB: Molded-case circuit breaker.
- C. MCP: Motor circuit protector.
- D. NC: Normally closed.
- E. OCPD: Overcurrent protective device.
- F. SCCR: Short-circuit current rating.
- G. SCPD: Short-circuit protective device.

1.4 ACTION SUBMITTALS

- A. Product Data: For each type of product.
 - 1. Include rated capacities, operating characteristics, electrical characteristics, and furnished specialties and accessories.

1.5 DELIVERY, STORAGE, AND HANDLING

- A. Store controllers indoors in clean, dry space with uniform temperature to prevent condensation. Protect controllers from exposure to dirt, fumes, water, corrosive substances, and physical damage.

1.6 FIELD CONDITIONS

- A. Ambient Environment Ratings: Rate equipment for continuous operation under the following conditions unless otherwise indicated:
 - 1. Ambient Temperature: Not less than 23 deg F and not exceeding 104 deg F.
 - 2. Altitude: Not exceeding 6600 feet for electromagnetic and manual devices.
 - 3. The effect of solar radiation is not significant.

PART 2 - PRODUCTS

2.1 PERFORMANCE REQUIREMENTS

- A. Electrical Components, Devices, and Accessories: Listed and labeled as defined in NFPA 70, by a qualified testing agency, and marked for intended location and use.
- B. UL Compliance: Fabricate and label magnetic motor controllers to comply with UL 508 and UL 60947-4-1.
- C. NEMA Compliance: Fabricate motor controllers to comply with ICS 2.

2.2 MANUAL MOTOR CONTROLLERS

- A. Motor-Starting Switches (MSS): "Quick-make, quick-break" toggle or push-button action; marked to show whether unit is off or on.
 - 1. Standard: Comply with NEMA ICS 2, general purpose, Class A.
 - 2. Configuration: Nonreversing .
 - 3. Surface mounting.
 - 4. Red pilot light.
- B. Fractional Horsepower Manual Controllers (FHPMC): "Quick-make, quick-break" toggle or push-button action; marked to show whether unit is off, on, or tripped.
 - 1. Configuration: Nonreversing .
 - 2. Overload Relays: Inverse-time-current characteristics; NEMA ICS 2, Class 10 tripping characteristics; heaters matched to nameplate full-load current of actual protected motor; external reset push button ; bimetallic type .
 - 3. Pilot Light: Red .

2.3 COMBINATION FULL-VOLTAGE MAGNETIC MOTOR CONTROLLER

- A. Description: Factory-assembled, combination full-voltage magnetic motor controller consisting of the controller described in this article, indicated disconnecting means, SCPD and OCPD, in a single enclosure.
- B. Standard: Comply with NEMA ICS 2, general purpose, Class A.
- C. Configuration: Nonreversing .
- D. Contactor Coils: Pressure-encapsulated type with coil transient suppressors when indicated.
 - 1. Operating Voltage: Manufacturer's standard, unless indicated.
- E. Control Power:
 - 1. For on-board control power, obtain from line circuit or from integral CPT. The CPT shall have capacity to operate integral devices and remotely located pilot, indicating, and control devices.
- F. Overload Relays:
 - 1. Thermal Overload Relays:
 - a. Inverse-time-current characteristic.
 - b. Class 10 tripping characteristic.
 - c. Heaters in each phase shall be matched to nameplate full-load current of actual protected motor and with appropriate adjustment for duty cycle.
 - d. Ambient compensated.
 - e. Automatic resetting.
- G. Digital communication module, using RS-485 Modbus, RTU protocol, 2 -wire connection to host devices with a compatible port] to transmit the following to the LAN:
 - 1. Instantaneous rms current each phase, and 3-phase average.
 - 2. Voltage: L-L for each phase, L-L 3-phase average, L-N each phase and L-N 3-phase average - rms.
 - 3. Active Energy (kWh): 3-phase total.
 - 4. Power Factor: Each phase and 3-phase total.

PART 3 - EXECUTION

3.1 EXAMINATION

- A. Examine areas and space conditions for compliance with requirements for motor controllers, their relationship with the motors, and other conditions affecting performance of the Work.

3.2 INSTALLATION

- A. Comply with NECA 1.
- B. Wall-Mounted Controllers: Install magnetic controllers on walls with tops at uniform height indicated, and by bolting units to wall or mounting on lightweight structural-steel channels bolted to wall. For controllers not at walls, provide freestanding racks complying with Section 26 05 29 "Hangers and Supports for Electrical Systems" unless otherwise indicated.
- C. Comply with requirements for seismic control devices specified in Section 26 05 48.16 "Seismic Controls for Electrical Systems."
- D. Maintain minimum clearances and workspace at equipment according to manufacturer's written instructions and NFPA 70.
- E. Wiring within Enclosures: Bundle, lace, and train conductors to terminal points with no excess and without exceeding manufacturer's limitations on bending radii. Install lacing bars and distribution spools.
- F. Setting of Overload Relays: Select and set overloads on the basis of full-load current rating as shown on motor nameplate. Adjust setting value for special motors as required by NFPA 70 for motors that are high-torque, high-efficiency, and so on.

3.3 SYSTEM FUNCTION TESTS

- A. System function tests shall prove the correct interaction of sensing, processing, and action devices. Perform system function tests after field quality control tests have been completed and all components have passed specified tests.
 - 1. Develop test parameters and perform tests for the purpose of evaluating performance of integral components and their functioning as a complete unit within design requirements and manufacturer's published data.
 - 2. Verify the correct operation of interlock safety devices for fail-safe functions in addition to design function.
 - 3. Verify the correct operation of sensing devices, alarms, and indicating devices.
- B. Motor controller will be considered defective if it does not pass the system function tests and inspections.
- C. Prepare test and inspection reports.

END OF SECTION 26 29 13.03